

Reputation-based Resilient Distributed Algorithms

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Coimbra

October 18th 2019

Outline

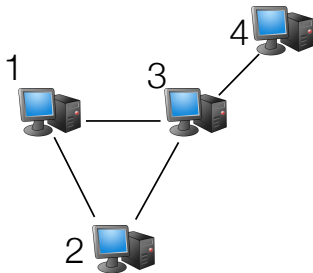
- 1 Introduction
- 2 Problem Statement
- 3 Proposed Solution
- 4 Simulation Results
- 5 Concluding Remarks

Motivation

- Compute the average of samples - a set of sensors produces measurements that require some gathering approach.
- No centralized supervision - there does not exist an entity establishing the quality of the measurements.
- Lightweight removal of attackers - proposed solutions need to require a low computational cost.

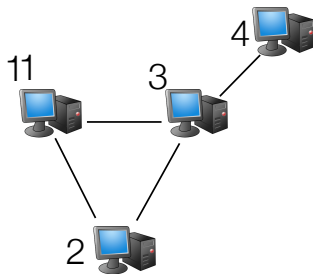
Example

- Take the network given by the following graph and state at time instant k ,
 $x(k) = [1, 2, 3, 4]^T$
- The consensus algorithm will asymptotically converge to all the nodes having $x_{av} = 2.5$
- If an attacker controlling one node in one time instant resets the state to
 $\tilde{x}_1(k) = x_1(k) + m(c - x_{av})$
- In this example $c = 5$, but the attacker can force the network to converge to any constant c !



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Traditional Solutions

- 1 Centralized approach
- 2 Use of an additional layer that computes worst-case values for the measurements [1][2].
- 3 Discard measurements from the computation that are at the extremes [3].

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- ③ *Low computational costs but cannot distinguish relevant data.*

Intuition behind Reputation-based approach

- In our daily lives, we are drawn towards decisions based on reputation.
- Reputation is a metric that assigns a large value if data is *similar*.
- Is suitable for distributed computation as processors can use the reputation to weight the data.

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Problem Statement

- Consider an iterative algorithm to compute some weighted average of the measurements:

$$x_i^{(k+1)} = \sum_{j \in \mathcal{N}_i} c_{ij}^{(k)} x_j^{(k)} / \sum_{j \in \mathcal{N}_i} c_{ij}^{(k)} \quad (1)$$

- Can we compute weights $c_{ij}^{(k)}$ such that:

$$\forall i \in \mathcal{N} \setminus \mathcal{A} : x_i^{(k+1)} \rightarrow \bar{x} \quad (2)$$

Resilient Consensus Problem

Can we design an algorithm that assigns weights based on reputation?

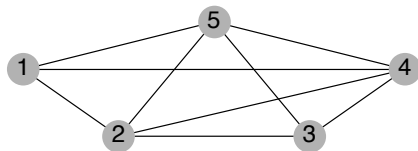
Reputation-based Consensus Algorithm

- We use work on reputation systems with some mathematical adjustments to compute $c_{ij}^{(k)}$;
- It has $\mathcal{O}(l^2 i)$ complexity for the maximum degree l and i iterations;
- No false positives;
- Has a better behavior than discarding extreme values in simulation.

Simulation - no attack

The figure illustrates the used topology.

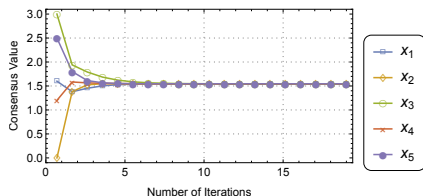
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- In the absence of attackers, reputations eventually equal 1.
- The algorithm converges to a consensus state.



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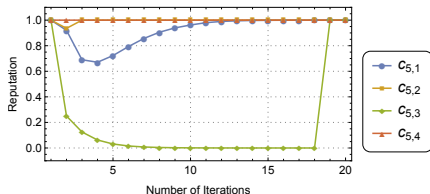
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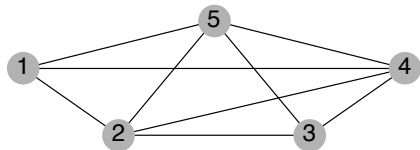
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Simulation - single attacker with value close to consensus

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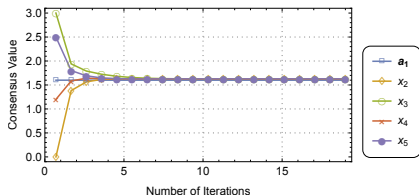
- At first sight it seems unsuccessful.
- By zooming in, we see that the nodes exclude the close value of the attacker.
- By looking at the reputation of node 5, the correct identification is clear.



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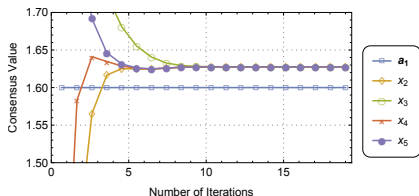
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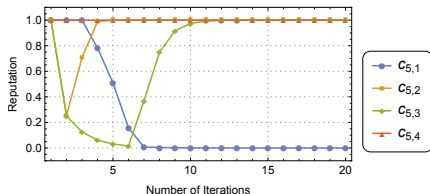
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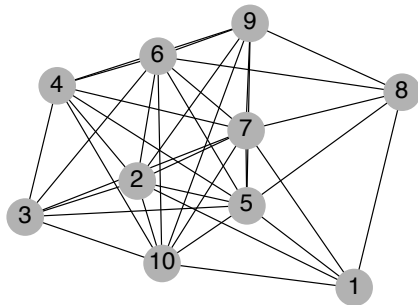
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Simulation - two attackers with different values

More complex topology.

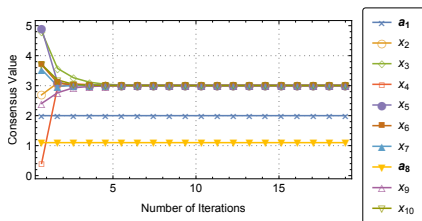
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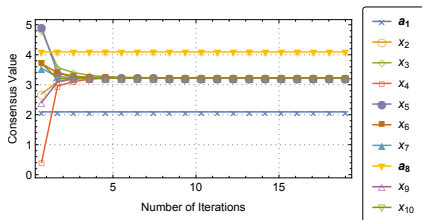
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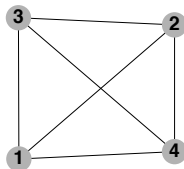
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Simulation - Reputation-based vs State-of-the-art (1/2)

State-of-the-art consists in removing large and small values. We used the topology in the figure.

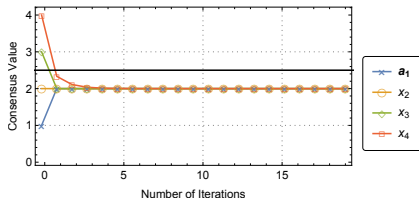
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- Using Reputation-based improves on minimizing the effect of the attacker.



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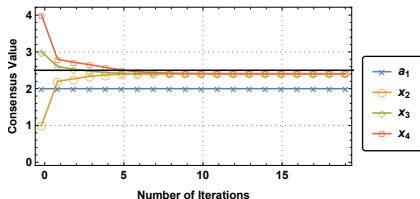
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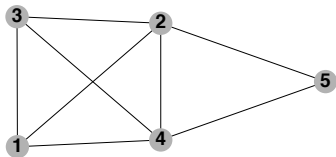
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Simulation - Reputation-based vs State-of-the-art (2/2)

Using a topology that is not fully connected.

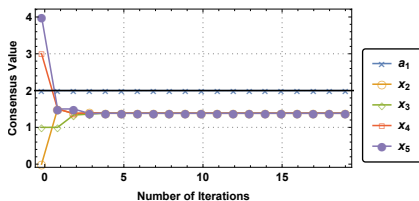
- Using MSR algorithm still results in a large shift in the steady-state.
- Using Reputation-based achieves a very small error.
- Even if the attacker uses a variable signal, using Reputation-based is still able to eliminate the influence.



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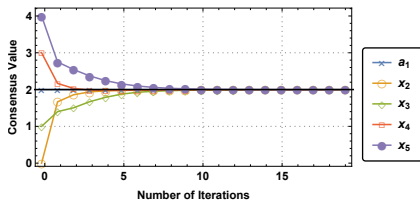
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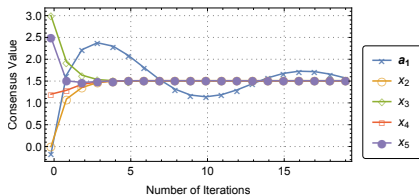
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Concluding Remarks

Contributions:

- We present a Reputation-based algorithm that measures the quality of the values provided by each agent.
- The algorithm is lightweight with worst-case complexity dependent on the largest number of neighbors.
- Currently, this work is under review. In the journal version, we provide theoretical guarantees associated with the correctness and correct detection.
- We have also tested other networks (static and dynamics), type of attacker signal, number of attackers, among others.

References

-  D. Silvestre, J. P. Hespanha, and C. Silvestre, “Broadcast and gossip stochastic average consensus algorithms in directed topologies,” *IEEE Transactions on Control of Network Systems*, vol. 6, no. 2, pp. 474–486, 2019. DOI: 10.1109/TCNS.2018.2839341.
-  D. Silvestre, P. Rosa, J. P. Hespanha, and C. Silvestre, “Stochastic and deterministic fault detection for randomized gossip algorithms,” *Automatica*, vol. 78, pp. 46 –60, 2017, ISSN: 0005-1098. DOI: 10.1016/j.automatica.2016.12.011.
-  H. Y. Öksüz and M. Akar, “Distributed resilient consensus: A non-parametric approach,” *Transactions of the Institute of Measurement and Control*, vol. 41, no. 8, pp. 2124–2134, 2019. DOI: 10.1177/0142331218785673.

The end

- Thank you for your time.

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